#### Lecture 1: Line Integral

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Vector Analysis

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#### Outline for section 1



2 Integral of Vector Field

3 Integral of 1-Form

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#### Object

- What is a curve in  $\mathbb{R}^d$ ?
- How to define a integral for along a curve  $\gamma$  as

 $\int_{\gamma} f \, d\gamma?$ 

• Similar property as Newton-Leibniz formula that

$$\int_{\gamma} f \, d\gamma = F(b) - F(a)?$$

You know the answer for a special case when  $\gamma$  is an affine interval.

#### What is a curve ?

- A curve in  $\mathbb{R}^d$  is a continuous parametrization  $\gamma : [a, b] \to \mathbb{R}^d$ .
- Thus, geometrically, two parametrizations  $\gamma_1, \gamma_2$  may identify a same object visually. (A non-math description.)
- One can establish an equivalent relation :  $\gamma_1 : [a, b] \to \mathbb{R}^d, \gamma_2 : [c, d] \to \mathbb{R}^d, \gamma_1 \equiv \gamma_2$  if there is a monotone bijection  $\phi : [a, b] \to [c, d]$  and

$$\forall t \in [a, b], \qquad \gamma_2(\phi(t)) = \gamma_1(t).$$

#### Curve

#### Length of a Curve

One natural way to define the length of a curve  $\gamma : [a, b] \to \mathbb{R}^d$  is to do at first partition  $\mathcal{P}$  and then let the partition go to 0. That is: Let  $\mathcal{P} = \{t_0, t_1 \cdots t_n\}$  where  $a = t_0 < t_1 \cdots < t_n = b$ , and  $|\mathcal{P}| = \max_{0 \leq i \leq n-1} |t_{i+1} - t_i|$ , then the length of the curve with the partition  $L(\gamma, \mathcal{P})$  is

$$L(\gamma, \mathcal{P}) = \sum_{i=0}^{n-1} |\gamma(t_{i+1}) - \gamma(t_i)|. \qquad (1.1)$$

One may define that

$$L(\gamma) := \lim_{|\mathcal{P}| \to 0} L(\gamma, \mathcal{P}).$$
(1.2)

## Length of a Curve

#### Definition (Rectified Curve)

We say a curve  $\gamma : [a, b] \to \mathbb{R}^d$  is rectified if eq. (1.2) is well defined and  $L(\gamma) < \infty$ . In this case, we say  $L(\gamma)$  the length of  $\gamma$ .

#### Curve

#### Length of a Curve

- It is false that every curve has length, even it is continuous.
- Reason: fractal structure.
- e.x. Koch's snowflake, Brownian motion etc.

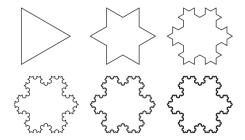


Figure: Koch's snowflake.

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# Length of a Curve

Remark: For these fractal objects, although the definition of length above does not work, one can also define their "length" by some other formula.

# Length of a Curve

#### Theorem

If  $\gamma : [a, b] \to \mathbb{R}^d$  is  $C^1$ , then  $L(\gamma)$  exists.

#### Proof.

In this case  $|\gamma(t_{i+1}) - \gamma(t_i)| \simeq \gamma'(t_i)|t_{i+1} - t_i|$ , and one can use the uniform continuity to prove that the sum converges.

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# Regular Curve

#### Definition (Regular Curve)

We say a curve  $\gamma : [a, b] \to \mathbb{R}^d$  is regular is  $\gamma$  is  $C^1([a, b])$  and  $\gamma' \neq 0$ .

#### Definition (Equivalent Relation for Regular Curve)

For two regular curves  $\gamma_1 : [a, b] \to \mathbb{R}^d$ ,  $\gamma_2 : [c, d] \to \mathbb{R}^d$ , we say they are equivalent if there is a monotone  $C^1$  bijection  $\phi : [a, b] \to [c, d]$  and

$$\forall t \in [a, b], \qquad \gamma_2(\phi(t)) = \gamma_1(t).$$

#### Theorem (Integral along Regular Curve)

For a regular curve  $\gamma:[a,b]\to \mathbb{R}^d,$  f continuous on  $\gamma,$  then we define that

$$\int_{\gamma} f \, d\gamma := \int_{a}^{b} f(\gamma(t)) |\gamma'(t)| \, dt.$$
(1.3)

This integral is independent of the parametrization: for two equivalent regular curves  $\gamma_1 : [a, b] \to \mathbb{R}^d, \gamma_2 : [c, d] \to \mathbb{R}^d$ , we have

$$\int_{a}^{b} f(\gamma_{1}(t)) |\gamma_{1}'(t)| dt = \int_{c}^{d} f(\gamma_{2}(t)) |\gamma_{2}'(t)| dt.$$
(1.4)

**Remark:** One can generalize this result to a curve regular in every interval.

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#### Proof.

Let  $\phi : [a, b] \rightarrow [c, d]$  the function such that  $\gamma_1 = \gamma_2 \circ \phi$ , and let  $s = \phi(t)$ , then we have

$$\begin{split} \int_{a}^{b} f(\gamma_{1}(t)) |\gamma_{1}'(t)| \, \mathrm{d}t &= \int_{a}^{b} f(\gamma_{2} \circ \phi(t)) |(\gamma_{2} \circ \phi(t))'| \, \mathrm{d}t \\ &= \int_{a}^{b} f(\gamma_{2}(\phi(t))) |\gamma_{2}'(\phi(t))| \phi'(t) \, \mathrm{d}t \\ &= \int_{c}^{d} f(\gamma_{2}(s)) |\gamma_{2}'(s)| \, \mathrm{d}s. \end{split}$$

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Interpretation 1 of the equation

$$\int_a^b f(\gamma_1(t))|\gamma_1'(t)|\,\mathrm{d} t = \int_c^d f(\gamma_2(t))|\gamma_2'(t)|\,\mathrm{d} t.$$

: Alice and Bob finish a riding tour and they count the number of the audience, which has density f. Alice has trace  $\gamma_1$  during time [a, b] while Bob with trace  $\gamma_2$  during time [c, b]. If we suppose they finish the same tour, with the same audience, the total number does not depend on how and when they finish.

Interpretation 2 of the equation

$$\int_a^b f(\gamma_1(t))|\gamma_1'(t)|\,\mathrm{d} t = \int_c^d f(\gamma_2(t))|\gamma_2'(t)|\,\mathrm{d} t.$$

Let f be the mass density of a string, then this equation calculate the total mass of this string, which is

$$\lim_{|\mathcal{P}| \to 0} \sum_{i=0}^{n-1} f(t_i) |\gamma(t_{i+1}) - \gamma(t_i)|.$$

#### Outline for section 2



2 Integral of Vector Field



# Work done by the force

Let a particle moving along the curve  $\gamma : [a, b] \to \mathbb{R}^d$ , drive by a force field  $F : \mathbb{R}^d \to \mathbb{R}^d$ , then what is the work done by the force ?

- Recall the formula:  $W = F \cdot \Delta S$ .
- We do a partition  $\mathcal{P}$  of the curve,  $\mathcal{P} = \{t_0, t_1 \cdots t_n\}$  where  $a = t_0 < t_1 \cdots < t_n = b$ , and  $|\mathcal{P}| = \max_{0 \le i \le n-1} |t_{i+1} t_i|$
- We use linear interpolation and suppose the force constant on every interval, then

$$W(\gamma, F, \mathcal{P}) = \sum_{i=0}^{n-1} F(t_i) \cdot (\gamma(t_{i+1}) - \gamma(t_i)).$$

• We take the limit

$$W(\gamma, F) = \lim_{|\mathcal{P}| \to 0} W(\gamma, F, \mathcal{P}).$$

#### Work done by the force

#### Question: How to make the procedure above rigorous ?

# Integral of Vector Field

#### Theorem (Integral of Vector Field)

Let  $\gamma : [a, b] \to \mathbb{R}^d$  a regular curve (so  $C^1([a, b])$ , with d components  $(\gamma_1, \gamma_2 \cdots \gamma_d)$ . Let the force field  $F : \mathbb{R}^d \to \mathbb{R}^d$  a continuous field, i.e.

$$\mathbf{F} = (\mathbf{F}_1, \mathbf{F}_2, \cdots \mathbf{F}_d), \forall \mathbf{i}, \mathbf{F}_\mathbf{i} \in \mathbf{C}(\mathbb{R}^d).$$

Then we define that

$$\int_{\gamma} F \, \mathrm{d}\gamma := \int_{a}^{b} F(t) \cdot \gamma'(t) \, \mathrm{d}t = \sum_{i=1}^{d} \int_{a}^{b} F_{i}(t) \gamma'_{i}(t) \, \mathrm{d}t.$$

Moreover, for two equivalent regular curves  $\gamma, \beta$ , we have

$$\int_{\gamma} \mathbf{F} \, \mathrm{d}\gamma = \int_{\beta} \mathbf{F} \, \mathrm{d}\beta$$

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# Gradient Field

#### Definition (Gradient Field)

 $F:\mathbb{R}^d\to\mathbb{R}^d$  is a gradient field if and only if there exists  $f:\mathbb{R}^d\to\mathbb{R}$  differentiable such that

$$\mathbf{F} = \nabla \mathbf{f}, \qquad \text{i.e.} \qquad \mathbf{F}_{\mathbf{i}} = \partial_{\mathbf{i}} \mathbf{f}.$$

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# Integral of Gradient Field

Lemma

Let  $\gamma:[0,1]\to\mathbb{R}^d$  a regular curve, F a continuous gradient field that  $F=\nabla f,$  then

$$\int_{\gamma} \operatorname{F} \mathrm{d} \gamma = \operatorname{f}(\gamma(1)) - \operatorname{f}(\gamma(0)).$$

In this case, we call f potential function.

# Integral of Gradient Field

#### Proof.

F continuous implies that  $f \in C^1(\mathbb{R}^d)$ , then we have  $t \mapsto f(\gamma(t)) \in C^1([0, 1])$ , we use Newton-Leibniz formula that

$$\begin{split} f(\gamma(1)) - f(\gamma(0)) &= \int_0^1 \frac{d}{dt} f(\gamma(t)) \, dt \\ &= \int_0^1 \nabla f(\gamma(t)) \cdot \gamma'(t) \, dt \\ &= \int_0^1 F(\gamma(t)) \cdot \gamma'(t) \, dt. \end{split}$$

It is the lemma.

# Integral of Gradient Field

As a corollary, for F continuous field, then  $\int_{\gamma} F d\gamma$  only depends on the end points rather than how they are connected.

#### Outline for section 3



2 Integral of Vector Field



The integral of vector field is in fact an integral of 1-form, which is a very intuitive example of the general integral of k-form. Objective of this section: start to be familiar with the terminology of differential form.

# Dual Space of $\mathbb{R}^d$

• We define the dual space of  $\mathbb{R}^d$ 

$$(\mathbb{R}^d)^* := \{T | T : \mathbb{R}^d \to \mathbb{R} \text{ linear function } \}.$$

•  $(\mathbb{R}^d)^*$  is itself a d dimension linear space. Since every linear map has form

$$T = \sum_{i=1}^{d} \alpha_i e_i^*, \qquad e_i^*(e_j) = \delta_{ij}, \qquad T(\sum_{i=1}^{d} x_i e_i) = \sum_{i=1}^{d} \alpha_i x_i.$$

# Dual Space of $\mathbb{R}^d$

#### Proof.

We test T with  $\{e_1 \cdots e_d\}$  that

$$\forall 1 \leq i \leq d, \quad \alpha_i := T(e_i).$$

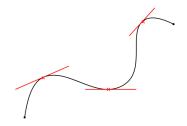
Then, for any  $x = \sum_{i=1}^{d} x_i e_i$ , we have

$$\mathrm{T}(\mathrm{x}) = \mathrm{T}(\sum_{\mathrm{i}=1}^{\mathrm{d}} \mathrm{x}_{\mathrm{i}} \mathrm{e}_{\mathrm{i}}) = \sum_{\mathrm{i}=1}^{\mathrm{d}} \mathrm{x}_{\mathrm{i}} \mathrm{T}(\mathrm{e}_{\mathrm{i}}) = \sum_{\mathrm{i}=1}^{\mathrm{d}} \alpha_{\mathrm{i}} \mathrm{x}_{\mathrm{i}}.$$

Let  $e_i^*$  such that  $e_i^*(e_j) = \delta_{ij}$ , then we have obviously  $T = \sum_{i=1}^d \alpha_i e_i^*$ .  $\Box$ 

# Tangent Space of Regular Curve

For a regular space  $\gamma : [a, b] \to \mathbb{R}^d$ , for every  $p \in (a, b)$ , it is associated to a tangent space  $T_p \gamma$  of dimension 1 and also a dual space  $T_p^* \gamma$  ( = cotangent space) of dimension 1.



Remark:  $\gamma' \neq 0$  is important here.

# Integral of 1-Form

- We revisit the vector field  $F : \mathbb{R}^d \to \mathbb{R}^d$ .
- F is considered as 1-form:

$$\mathbf{F} = \mathbf{F}_1 \mathbf{d} \mathbf{x}_1 + \mathbf{F}_2 \mathbf{d} \mathbf{x}_1 \cdots \mathbf{F}_d \mathbf{d} \mathbf{x}_d.$$

• For any 
$$p \in \gamma$$
,  $F(p) \in T_p^* \gamma$  that

$$\forall h \in T_p \gamma, \quad F(p)(h) = F(p) \cdot h.$$

•  $\int_{\gamma} F$  is understood as the integral of this linear functional - that is the integral of 1-form.

# Gradient as Exterior Differential of 0-form

- A function  $g : \mathbb{R}^d \to \mathbb{R}$  is 0-form.
- We define the exterior differential of a 0-form

$$dg = \sum_{i=1}^d \frac{\partial g}{\partial x_i} dx_i.$$

• A gradient vector field F is an 1-form such that F = dg, it is also said exact.

# Homotopy

#### Definition (Homotopic Function)

Two continuous curves  $\gamma_0,\gamma_1:[a,b]\to U\subset\mathbb{R}^d$  with the same end point

$$\gamma_0(\mathbf{a}) = \gamma_1(\mathbf{a}), \qquad \gamma_0(\mathbf{b}) = \gamma_1(\mathbf{b}).$$

They are homotopic if there exists a continuous function  $H: [0, 1] \times [a, b] \rightarrow U$  s.t.

$$\begin{split} H(0,\cdot) &= \gamma_0(\cdot), H(1,\cdot) = \gamma_1(\cdot), \\ \forall s \in [0,1], H(s,a) &= \gamma_0(a) = \gamma_1(a), \\ H(s,b) &= \gamma_0(b) = \gamma_1(b). \end{split}$$

H is called homotopy function for  $\gamma_0, \gamma_1$ .

# Homotopy

• The theorem for the gradient field can be stated as: the integral is equal for homotopic curves.

